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Optimal Channel Access Schemes for Wireless LAN under Asynchronous Multiple-Packet Reception (MPR)



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➤ Research Background

p -Persistent CSMA

A user begins a packet transmission with a common probability p when it has sensed channel idle, and continues sensing when it has sensed channel busy

Multiple-Packet Reception

Multiple-packet reception (MPR) techniques enable successful receptions of time-overlapping packets at the physical layer.

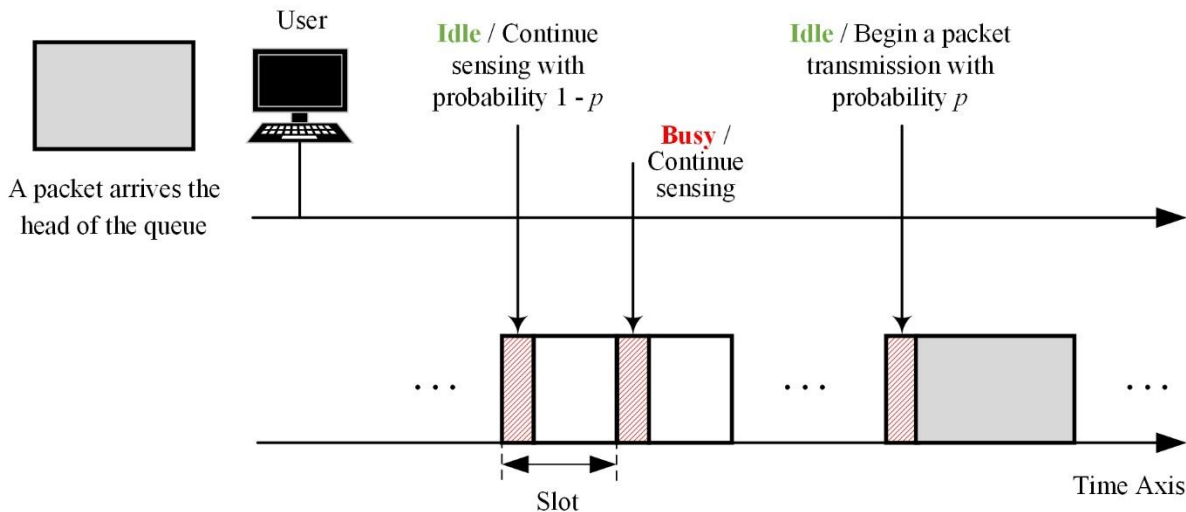


Figure 1. p -persistent CSMA

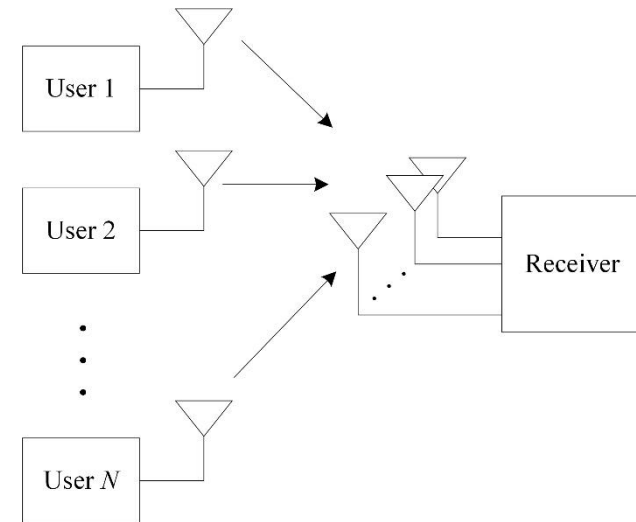
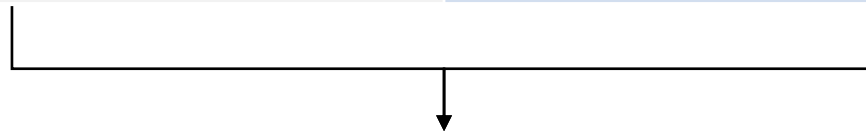


Figure 2. MPR techniques

➤ Research Background

Traditional p -persistent CSMA under **single-packet** reception (SPR)

Traditional p -persistent CSMA under **multiple-packet** reception (MPR)



Limitation 1

Early studies on p -persistent CSMA assumed the SPR model, which did not consider **the advance of MPR techniques**

Limitation 2

Further studies on p -persistent CSMA assumed the MPR model under the synchronous mode, which led to **bandwidth waste**

Limitation 3

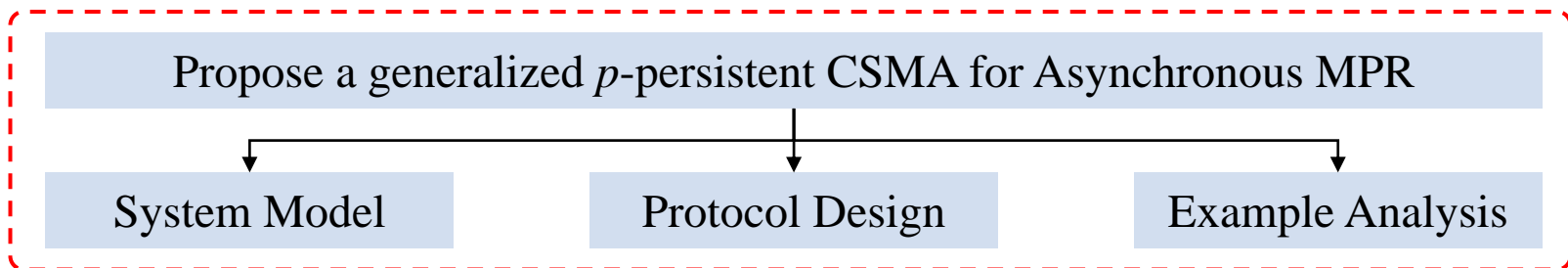
Although some early studies have improved the protocol, they do not provide **a general analytical model**, and **the setting of access probabilities are far from the optimum**

➤ System Model

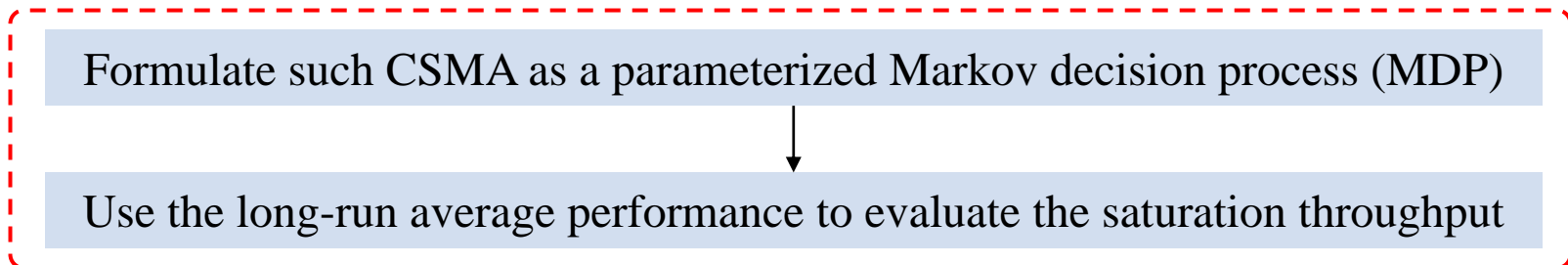
Carrier Sensing	We assume that all users can perform carrier sensing to detect if the number of ongoing transmissions is 0, ..., $\gamma - 1$ or $\geq \gamma$, and the time required to do so is negligible
Channel Assumption	We consider that wireless fading effect is negligible , and channel coding is not used to protect the packets.
γ-MPR Capability	We assume that the receiver has the γ-MPR capability , i.e., can recover all n signals simultaneously transmitted in a slot if $1 \leq n \leq \gamma$, and recover none of them otherwise.
Packet Length	We consider that the packet lengths correspond to integer numbers of slots , and follow the geometric distribution with average value $\Lambda > 1$

➤ Main Contributions

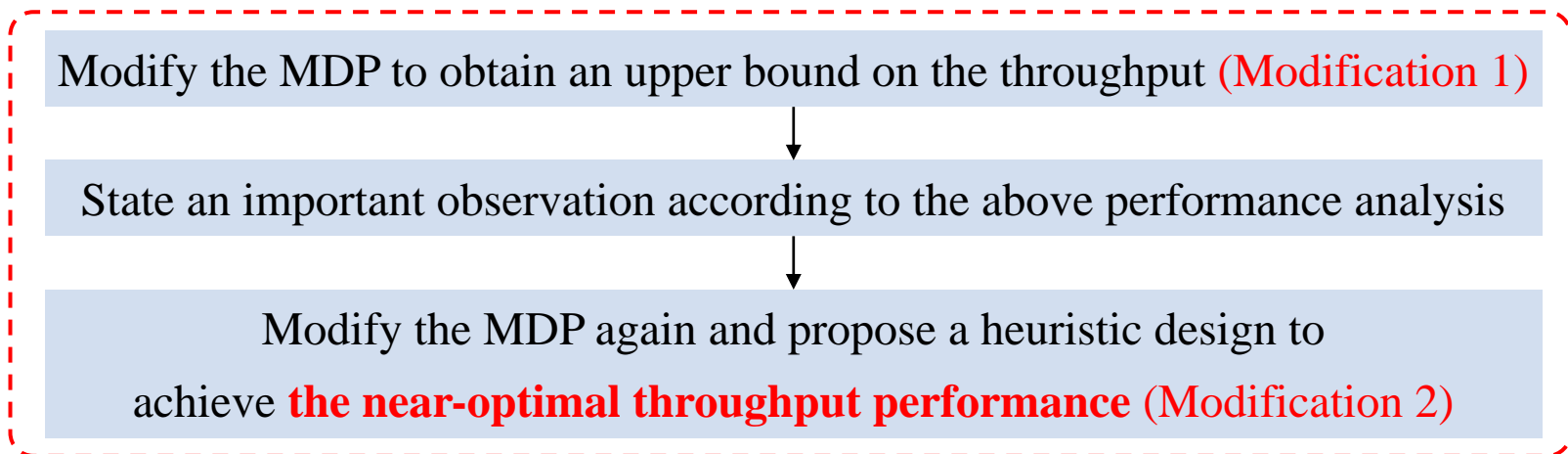
Contrib. 1



Contrib. 2



Contrib. 3



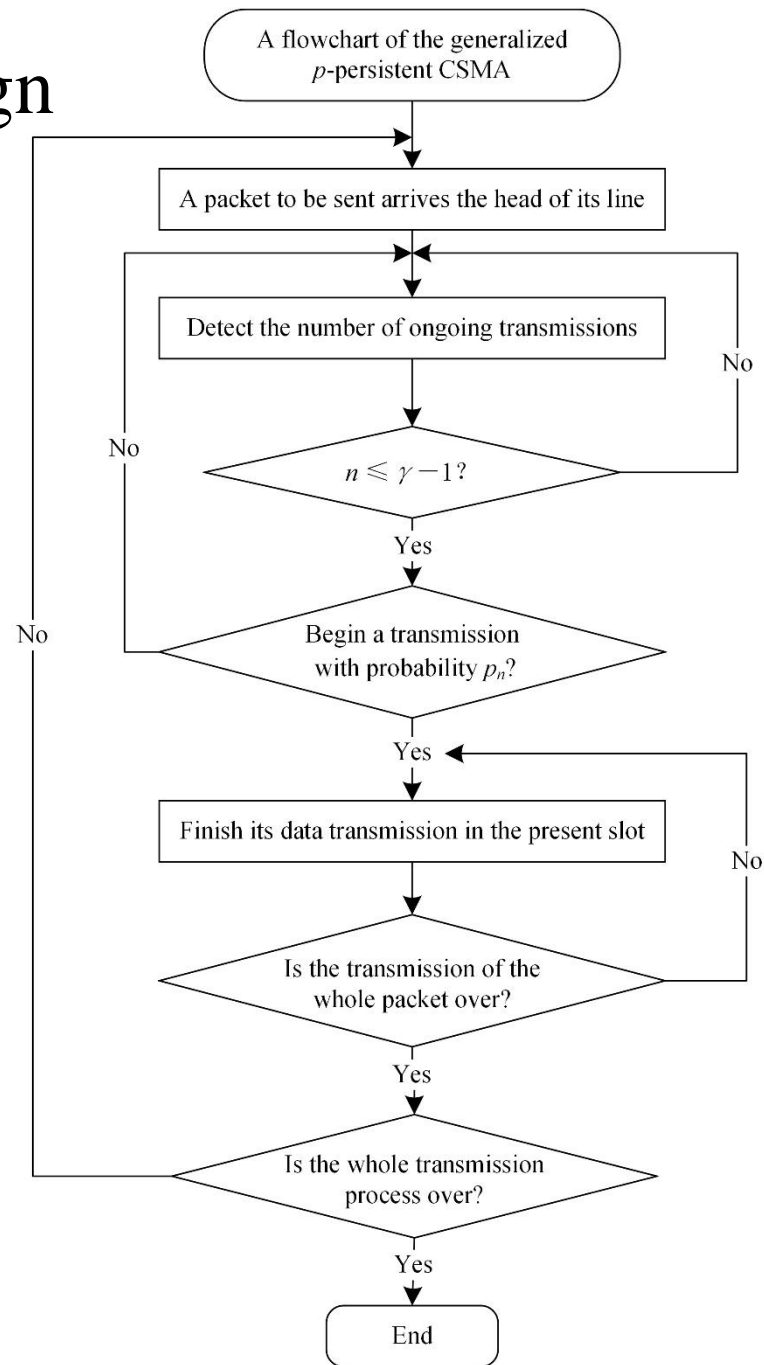
➤ Contrib. 1 Protocol Design

➤ Protocol Design

Each silent user is required to perform carrier sensing at the beginning of each time slot:

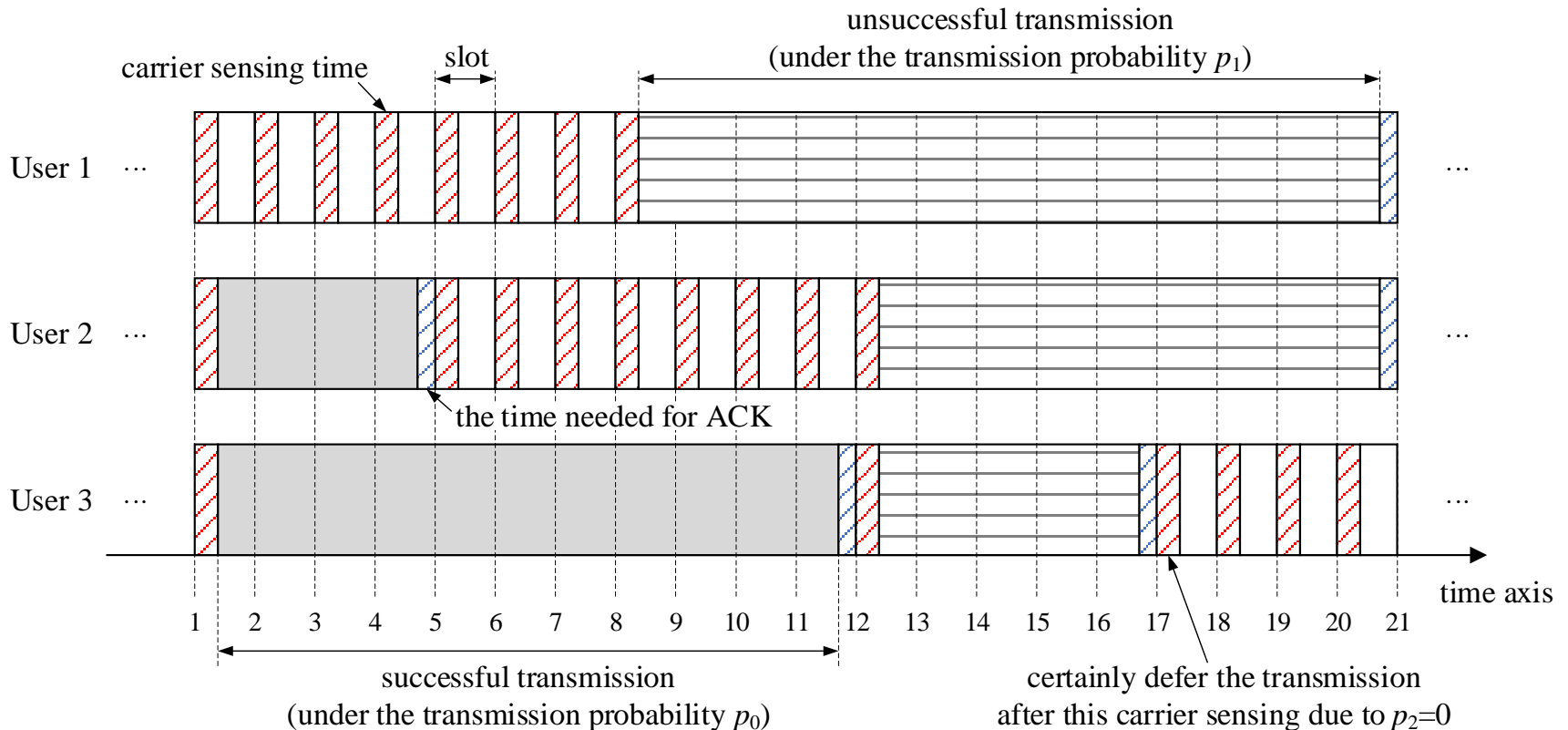
1. If this silent user detects $n < \gamma$ ongoing transmissions at the beginning of a slot, this user will begin a transmission with probability $0 \leq p_n < 1$;
2. Otherwise, this user will begin a transmission with probability $p_n = 0$.

Remark: The aforementioned system model with $\gamma = 1$ is exactly the model for p -persistent CSMA under SPR.



➤ Contrib. 1 Protocol Design

➤ The generalized p -persistent CSMA for the case of $N = 3$ and $\gamma = 2$.



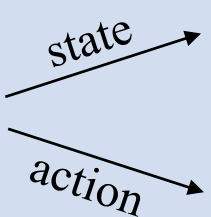
1. At the beginning of **slot 1**, **user 2** and **user 3** detect the number of ongoing transmission is **0**; thus they begin transmissions with probability p_0 .
2. At the beginning of **slot 8**, **user 1** detects the number of ongoing transmission is **1**; thus it begins a transmission with probability p_1 .

➤ Contrib. 2 Protocol Analysis

➤ Provide a general analytical model based on a parameterized MDP

Based on the access probability p_n , we define the parameter vector: $\mathbf{p} \triangleq (p_0, p_1, \dots, p_{\gamma-1})$



State	The state , denoted by n , is defined as the number of ongoing transmissions in the carrier sensing phase.
Action	The action , denoted by a , means that a users begin new transmissions after carrier sensing at state n .
Parameterized Policy	The parameterized policy , denoted by $\pi_{n,a}(\mathbf{p})$, is defined as the probability that a out of $N - n$ users begin to transmit at state n .
Transition Probability	The transition probability , denoted by $\varphi_{n,n'}(\mathbf{p})$, is defined as the probability that the next state is n' when the present state is n .
Reward	
	The state reward , denoted by $r_n(\mathbf{p})$, is defined as the average of total packet lengths of all the successful transmissions at state n .
	The action reward , denoted by $r_{n,a}(\mathbf{p})$, is defined as the reward which is achieved when action a is taken at state n .

➤ Contrib. 2 Protocol Analysis

➤ Theoretical analysis of the state reward $r_n(\mathbf{p})$

We assume that a given packet is being transmitted in both the present and next slots.

$\xi_{h,h'}(\mathbf{p})$

The probability that there are h' other ongoing transmissions in the next slot when there have been h other ongoing transmissions in the present slot.



$g_{m,h_1,h_m}(\mathbf{p})$

The probability that there are h_m other ongoing transmissions in the m -th slot of a given transmission, and fewer than γ other ongoing transmissions in each of the first $m-1$ slots of the transmission, provided that there are h_1 other ongoing transmissions in the first slot of the transmission.



$q_{\lambda,h_1}(\mathbf{p})$

The probability that a λ -slot transmission is successful when there are fewer than γ other ongoing transmissions in each of the λ slots of the transmission



$r_{n,a}(\mathbf{p})$

$r_n(\mathbf{p})$

Long-term average reward: $R(\mathbf{p}) \Rightarrow$ Throughput

➤ Contrib. 3 Protocol Optimization

➤ Definition of the optimization problem

Based on the access probability p_n , we define **the parameter vector**: $\mathbf{p} \triangleq (p_0, p_1, \dots, p_{\gamma-1})$

$\mathbf{p} \triangleq (p_0, p_1, \dots, p_{\gamma-1}) \subset \mathbb{D} \triangleq \mathbb{D}_0 \times \mathbb{D}_1 \times \dots \times \mathbb{D}_{\gamma-1}$, where $\mathbb{D}_0 \in (0,1)$, $\mathbb{D}_n \in [0,1)$ ($n \geq 1$)

Throughput $R(\mathbf{p})$ is a function of **the parameter vector \mathbf{p}** $\rightarrow \exists \mathbf{p} = \mathbf{p}_{opt} \Rightarrow R = R_{max}$

**Define the
optimization problem**

$$\mathbf{p}_{opt} = \arg \max_{\mathbf{p} \in \mathbb{D}} R(\mathbf{p}), \quad R_{max} = \max_{\mathbf{p} \in \mathbb{D}} R(\mathbf{p})$$

➤ Contrib. 3 Protocol Optimization

➤ Difficulties of the optimization problem

Search $\mathbb{D} \triangleq \mathbb{D}_0 \times \mathbb{D}_1 \times \dots \times \mathbb{D}_{\gamma-1} \rightarrow$ Find the optimal \mathbf{p} that maximizes $R(\mathbf{p})$



Modern Optimization Algorithms (such as Genetic Algorithm)

The algorithms possibly **takes a very long time** to find the near-optimal \mathbf{p} , and are required to **set opportune starting points**.

Gradient-Based Methods

The term $q_{\lambda,h1}(\mathbf{p})$ in $r_n(\mathbf{p})$ is **obtained recursively** and **the number of recursive steps** increases with the geometrically distributed packet length. \rightarrow The term $r_n(\mathbf{p})$ is difficult to be calculated.



A policy iteration type algorithm that optimizes a special category of parameterized MDPs



Two Conditions

1. The state space can be partitioned such that the transition probabilities and rewards of all states are affected by **a distinct parameter or none of parameters in \mathbf{p}** .
2. The change of the parameters in \mathbf{p} does not affect the conditional probability of the state value, known to be included in a partition.

➤ Contrib. 3 Protocol Optimization

➤ Difficulties of the optimization problem

Search $\mathbb{D} \triangleq \mathbb{D}_0 \times \mathbb{D}_1 \times \dots \times \mathbb{D}_{\gamma-1} \rightarrow$ Find the optimal \mathbf{p} that maximizes $R(\mathbf{p})$

The First Condition of the Policy Iteration

The state space can be partitioned such that the transition probabilities and rewards of all states are affected by **a distinct parameter or none of parameters in \mathbf{p}** .

The Researched Parameterized MDP

1. The reward $r_0(\mathbf{p})$ is affected by all the parameters in \mathbf{p}
2. The reward $r_n(\mathbf{p})$ for $0 < n < \gamma$ is affected by all the parameters in \mathbf{p} except p_0

MDP Modification

Mod. 1: Modify $r_n(\mathbf{p})$ to $r_n^*(\mathbf{p})$ and establish an upper bound on the throughput \rightarrow **Obtain an important observation** \rightarrow

Mod. 2: Modify $r_n(\mathbf{p})$ to $r_n^{**}(\mathbf{p})$ and propose a heuristic design

➤ Contrib. 3 Protocol Optimization

➤ Mod. 1: Establish an upper bound on the throughput

Reward
 $r_n(\mathbf{p})$

The reward, denoted by $r_n(\mathbf{p})$, is defined as the average of total packet lengths of **all the successful transmissions** at state n .

Reward
 $r_n^*(\mathbf{p})$

The reward, denoted by $r_n^*(\mathbf{p})$, is defined as the average of total packet lengths of the transmissions, each of which is **begun at state n** , and **received successfully at the first slot of its transmission**.

$$\rightarrow r_n^*(\mathbf{p}) = \Lambda \sum_{a=0}^{\gamma-n} a \cdot \pi_{n,a}(\mathbf{p}_n) \rightarrow R^*(\mathbf{p}) = \sum_{n=0}^{\gamma-1} \mu_n(\mathbf{p}) r_n^*(\mathbf{p})$$

→ Satisfy the first condition of the policy iteration

The packets overlap with $\gamma - 1$ or fewer other packets at the first slot of its transmission.

Definition of The Optimization Problem

$$\mathbf{p}_{upp} = \arg \max_{\mathbf{p} \in \mathbb{D}} R^*(\mathbf{p}), \quad R_{upp} = \max_{\mathbf{p} \in \mathbb{D}} R^*(\mathbf{p})$$

➤ Contrib. 3 Protocol Optimization

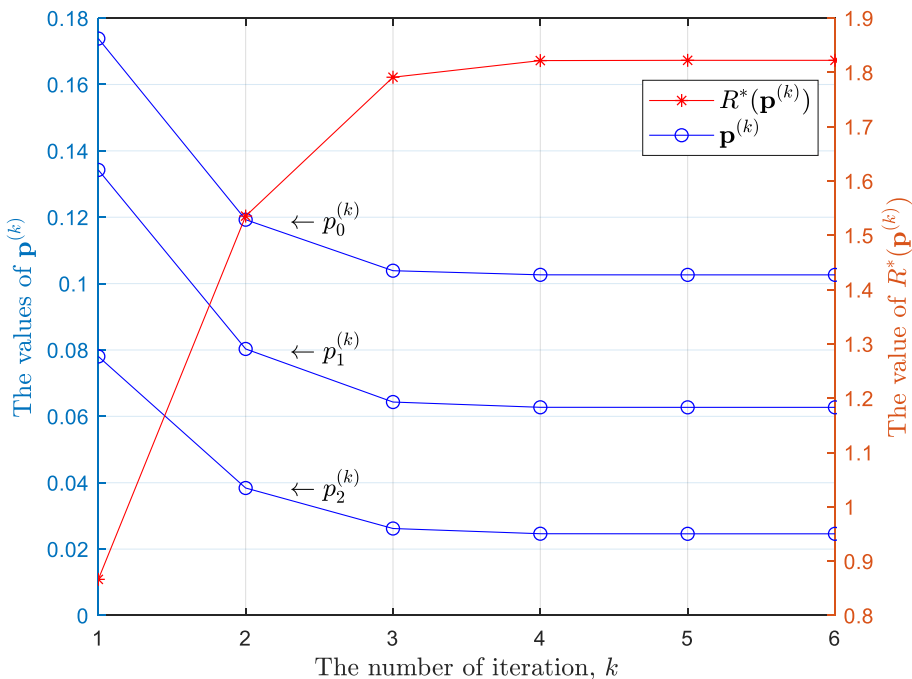
➤ Mod. 1: Solve \mathbf{p}_{upp} by the policy iteration (**Algorithm 1**)

1. Initialization	Choose an arbitrary parameter vector $\mathbf{p}^{(0)} \subset \mathbb{D}$ as the initial value and set $k = 0$.
2. Evaluation	Calculate the relative value $v_n^*(\mathbf{p}^{(k)})$ for each $n \in \mathcal{S}$ by Bellman equation.
3. Improvement	For $n = 0, 1, \dots, \gamma - 1$, update the new parameter as: $p_n^{(k+1)} = \arg \max_{p_n \in \mathbb{D}} r_n^*(p_n) + \sum_{n' \in \mathcal{S}} \phi_{n,n'}(p_n) v_{n'}^*(\mathbf{p}^{(k)})$
4. Stopping Rule	If $\mathbf{p}^{(k+1)} = \mathbf{p}^{(k)}$, set $\mathbf{p}_{upp} = \mathbf{p}^{(k)}$ and stop. Otherwise, set $k = k + 1$ and go to step 2.

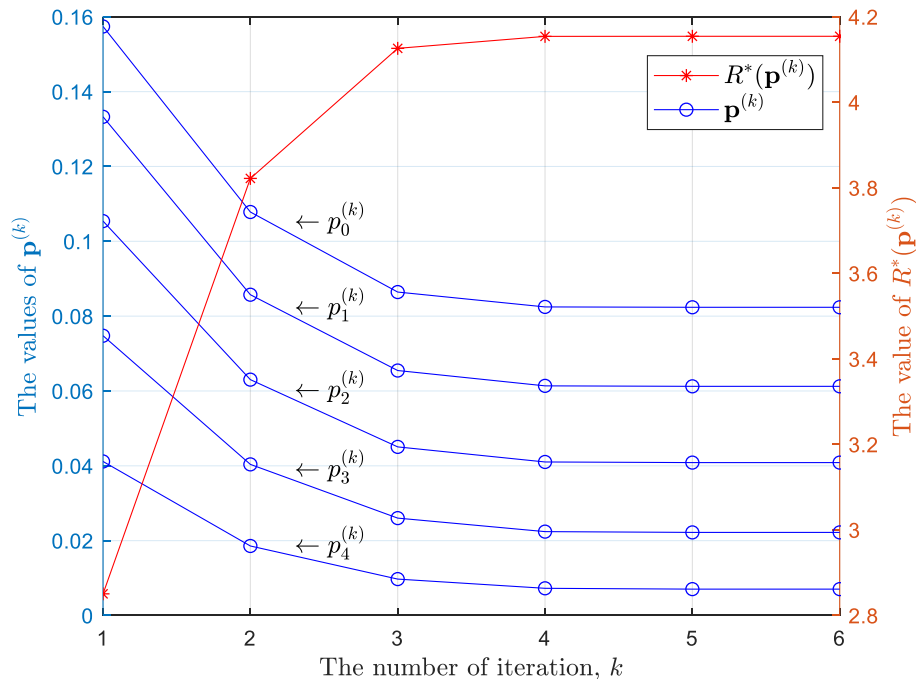
➤ Contrib. 3 Protocol Optimization

➤ Mod. 1: The iteration procedure of the parameters \mathbf{p} and $R^*(\mathbf{p})$

Parameters: $N=10, \gamma=3, \Lambda=20$



Parameters: $N=20, \gamma=5, \Lambda=50$



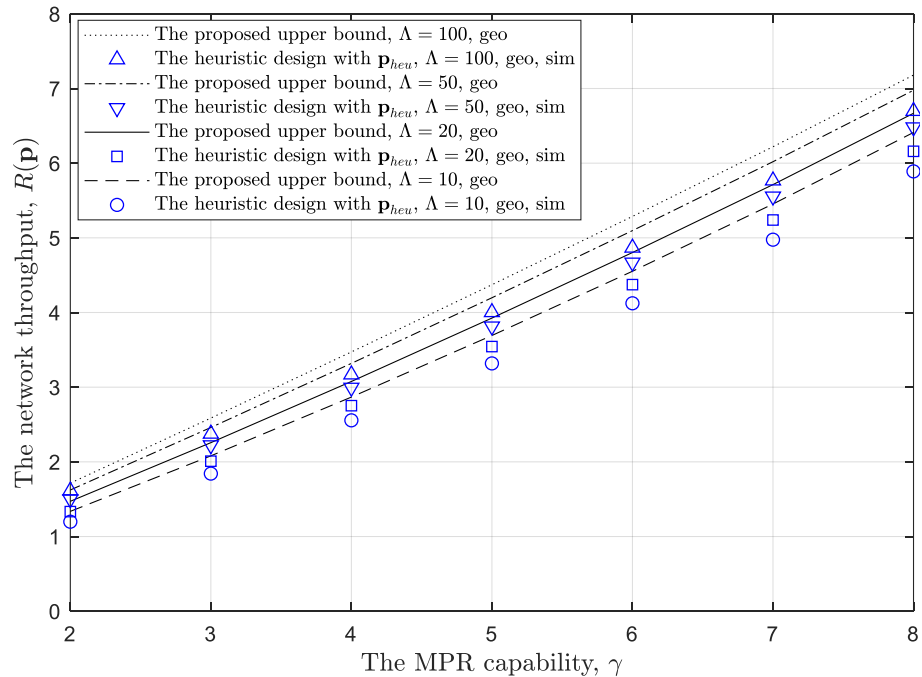
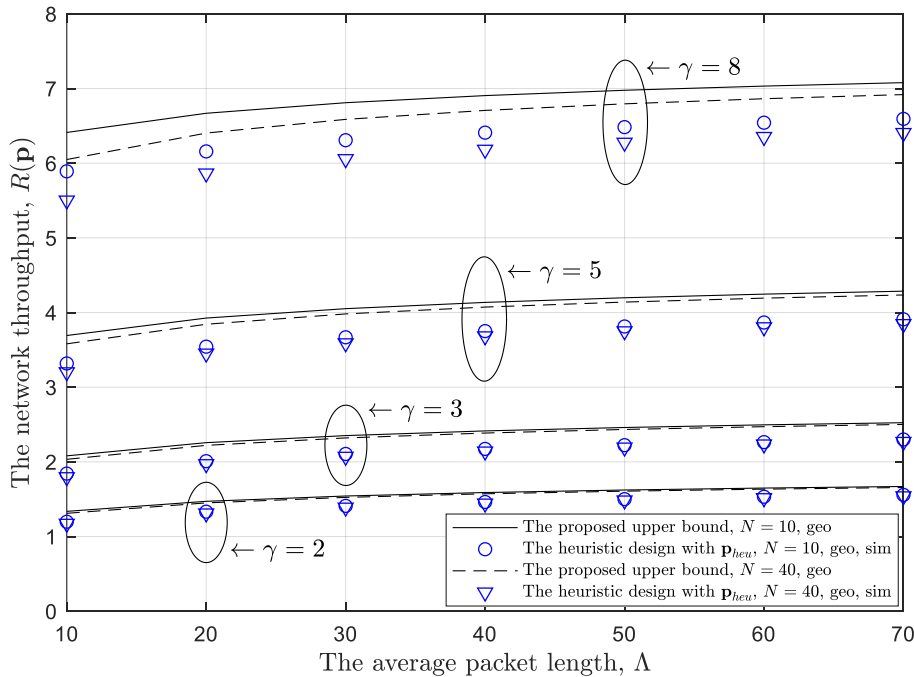
Initialization: We set $p_0^{(k)} = \gamma/N$, and $p_n^{(k)} = 0$ for $1 \leq n \leq \gamma - 1$.

Conclusion: It can be seen that only **6 iterations** are needed to satisfy the stopping rule.

➤ Contrib. 3 Protocol Optimization

➤ Mod 1: Comparisons between the throughput and its upper bound


Remark: We set the maximum number of allowed retransmissions to be infinitely large.



Conclusion: Relative gaps between the throughput performance and its upper bound are significant correlation with **the parameter Λ and the parameter γ**


➤ Contrib. 3 Protocol Optimization

➤ Mod. 2: Propose of the heuristic design

Reward $r_n(\mathbf{p})$	The reward, denoted by $r_n(\mathbf{p})$, is defined as the average of total packet lengths of all the successful transmissions at state n .
 Reward $r_n^{**}(\mathbf{p})$	<p>(I) If $n \geq \gamma$, no reward is gained.</p> <p>(II) If $n < \gamma$ and $0 \leq a \leq \gamma - n$, the total packet lengths of these a new transmissions are regarded as the positive reward.</p> <p>(III) If $n < \gamma$ and $\gamma - n < a \leq N - n$, no positive reward is gained and the total packet lengths of the n ongoing transmissions in the carrier sensing phase are regarded as the negative reward.</p> <p>→ $r_n^{**}(\mathbf{p}) = \Lambda \sum_{a=0}^{\gamma-n} a \cdot \mu_{n,a}(\mathbf{p}_n) - 2n\Lambda \sum_{a=\gamma-n+1}^{N-n} \mu_{n,a}(\mathbf{p}_n)$</p> <p>→ $R^{**}(\mathbf{p}) = \sum_{n=0}^{\gamma-1} \mu_n(\mathbf{p}) r_n^{**}(\mathbf{p})$</p> <p>→ Satisfy the first condition of the policy iteration</p>
Observation	When the system operates with \mathbf{p} whose values are close to \mathbf{p}_{opt} , there is a small probability that a transmission suffers from severe conflict .
Severe Conflict	If a given transmission collides with new transmissions at more than one slot , we say this transmission suffers from severe conflict.

➤ Contrib. 3 Protocol Optimization

➤ Mod. 2: Propose of the heuristic design

Reward $r_n(\mathbf{p})$	The reward, denoted by $r_n(\mathbf{p})$, is defined as the average of total packet lengths of all the successful transmissions at state n .
	<p>(I) If $n \geq \gamma$, no reward is gained.</p> <p>(II) If $n < \gamma$ and $0 \leq a \leq \gamma - n$, the total packet lengths of these a new transmissions are regarded as the positive reward.</p> <p>(III) If $n < \gamma$ and $\gamma - n < a \leq N - n$, no positive reward is gained and the total packet lengths of the n ongoing transmissions in the carrier sensing phase are regarded as the negative reward.</p> <p>→ $r_n^{**}(\mathbf{p}) = \Lambda \sum_{a=0}^{\gamma-n} a \cdot \mu_{n,a}(\mathbf{p}_n) - 2n\Lambda \sum_{a=\gamma-n+1}^{N-n} \mu_{n,a}(\mathbf{p}_n)$</p> <p>→ $R^{**}(\mathbf{p}) = \sum_{n=0}^{\gamma-1} \mu_n(\mathbf{p}) r_n^{**}(\mathbf{p})$</p> <p>→ Satisfy the first condition of the policy iteration</p>



Definition of The Optimization Problem	$\mathbf{p}_{heu} = \arg \max_{\mathbf{p} \in \mathbb{D}} R^{**}(\mathbf{p}), R_{heu} = \max_{\mathbf{p} \in \mathbb{D}} R(\mathbf{p}_{heu})$
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➤ Contrib. 3 Protocol Optimization

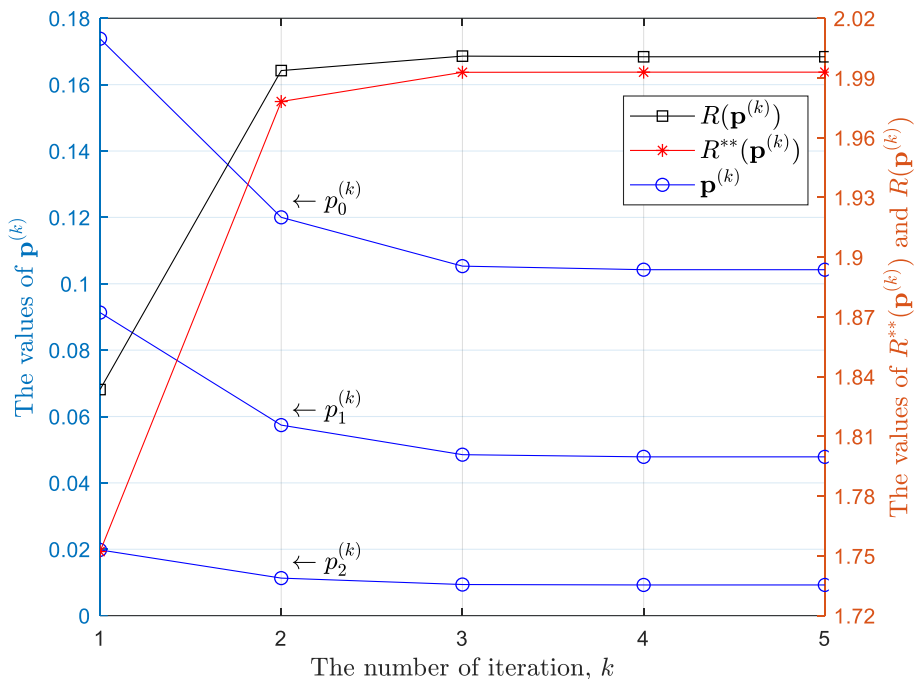
➤ Mod. 2: Solve \mathbf{p}_{heu} by the policy iteration (**Algorithm 2**)

1. Initialization	Choose an arbitrary parameter vector $\mathbf{p}^{(0)} \in \mathbb{D}$ as the initial value and set $k = 0$.
2. Evaluation	Calculate the relative value $v_n^*(\mathbf{p}^{(k)})$ for each $n \in \mathcal{S}$ by Bellman equation.
3. Improvement	For $n = 0, 1, \dots, \gamma - 1$, update the new parameter as: $p_n^{(k+1)} = \arg \max_{p_n \in \mathbb{D}} r_n^{**}(p_n) + \sum_{n' \in \mathcal{S}} \phi_{n,n'}(p_n) v_{n'}^{**}(\mathbf{p}^{(k)})$
4. Stopping Rule	If $\mathbf{p}^{(k+1)} = \mathbf{p}^{(k)}$, set $\mathbf{p}_{\text{upp}} = \mathbf{p}^{(k)}$ and stop. Otherwise, set $k = k + 1$ and go to step 2.

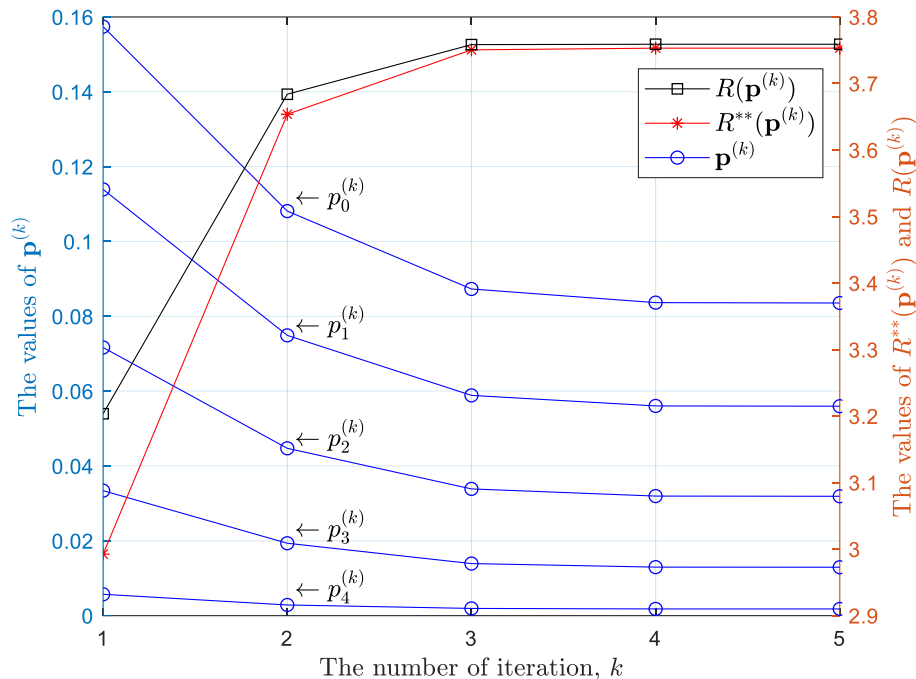
➤ Contrib. 3 Protocol Optimization

➤ Mod. 2: The iteration procedure of the parameters \mathbf{p} and $R^*(\mathbf{p})$

Parameters: $N=10, \gamma=3, \Lambda=20$



Parameters: $N=20, \gamma=5, \Lambda=50$



Initialization: We set $p_0^{(k)} = \gamma/N$, and $p_n^{(k)} = 0$ for $1 \leq n \leq \gamma - 1$.

Conclusion: It can be seen that only **5 iterations** are needed to satisfy the stopping rule.

➤ Contrib. 3 Protocol Optimization

➤ Mod 2: Comparisons between the heuristic design and *GlobalSearch (GS)*

The GS Solve (in *MATLAB Optimization Toolbox*) can be used to find global minima.

N	Algorithm	Time	p_0	p_1	p_2	p_3	p_4	R
10	<i>GS Solve</i>	4297.92s	0.22079	0.16006	0.09995	0.04517	0.00699	3.5353
	Heuristic Design	18.77s	0.22127	0.15934	0.09869	0.04402	0.00655	3.5348
12	<i>GS Solve</i>	2991.38s	0.17681	0.12568	0.07676	0.03384	0.00509	3.5090
	Heuristic Design	24.17s	0.17711	0.12505	0.07574	0.03295	0.00476	3.5085
14	<i>GS Solve</i>	2886.17s	0.14766	0.10358	0.06237	0.02708	0.00401	3.4928
	Heuristic Design	30.28s	0.14786	0.10303	0.06152	0.02635	0.00374	3.4923
16	<i>GS Solve</i>	5758.00s	0.12683	0.08814	0.05254	0.02257	0.00331	3.4818
	Heuristic Design	43.00s	0.12698	0.08765	0.05181	0.02196	0.00309	3.4813
18	<i>GS Solve</i>	19283.63s	0.11120	0.07673	0.04540	0.01936	0.00281	3.4738
	Heuristic Design	85.78s	0.11131	0.07629	0.04476	0.01883	0.00263	3.4733
20	<i>GS Solve</i>	29465.91s	0.09901	0.06795	0.03998	0.01694	0.00245	3.4678
	Heuristic Design	86.02s	0.09910	0.06754	0.03941	0.01648	0.00228	3.4672

Conclusion: The near-optimal parameter vectors and throughput solved in the heuristic design **are basically the same as** the optimal results solved by “GlobalSearch”.

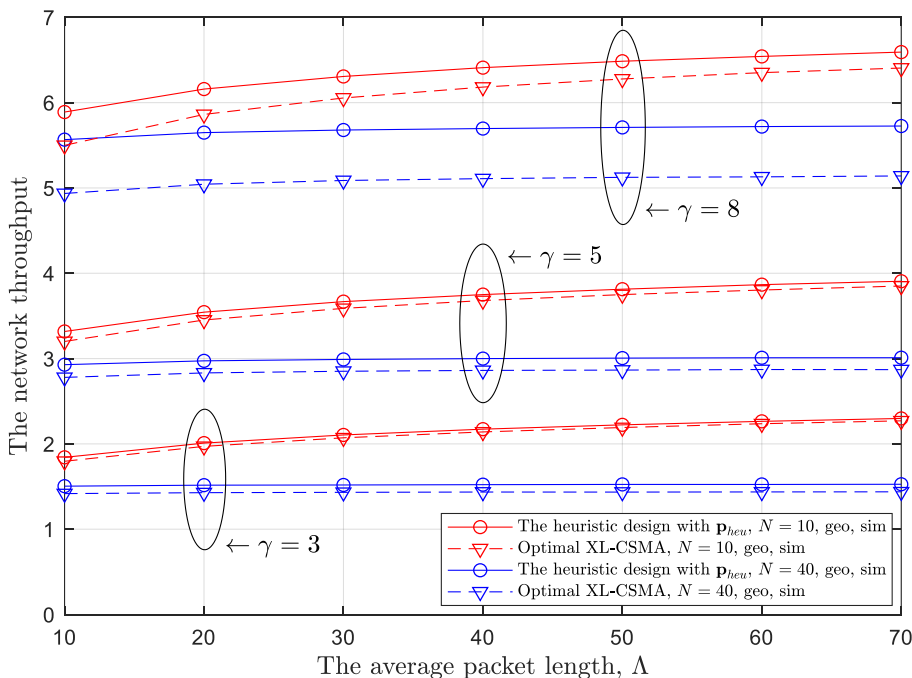
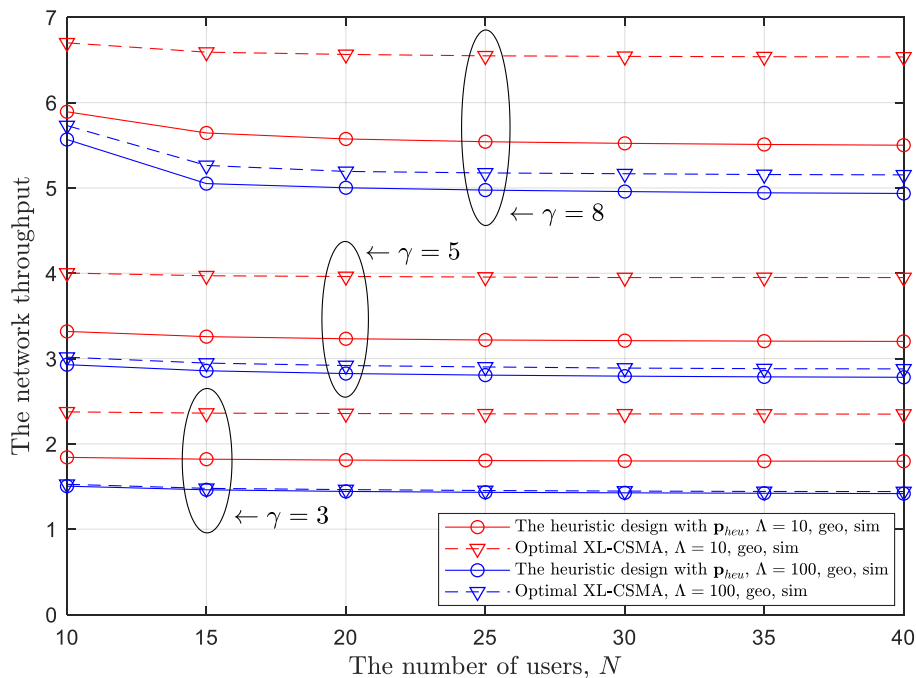
➤ Contrib. 3 Protocol Optimization

➤ Mod 2: Comparisons between the heuristic design and XL-CSMA

Remark: We set the maximum number of allowed retransmissions to be infinitely large.

XL-CSMA

Each user adopts the access probabilities $p_n = \max(0, (\gamma^* - n) / (N - n))$ for $n = 0, 1, \dots, \gamma - 1$, where the tuning parameter γ^* is an integer not larger than γ .



Conclusion: The heuristic design **significantly outperforms** optimal XL-CSMA in all the cases.

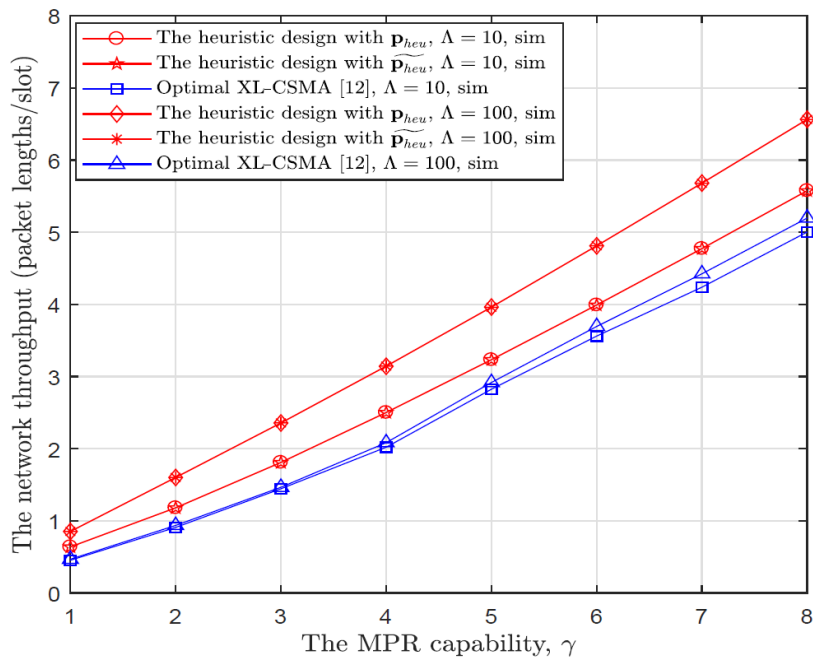
➤ Contrib. 3 Protocol Optimization

➤ Mod 2: Convert the generalized p -persistent CSMA to a CSMA/CA

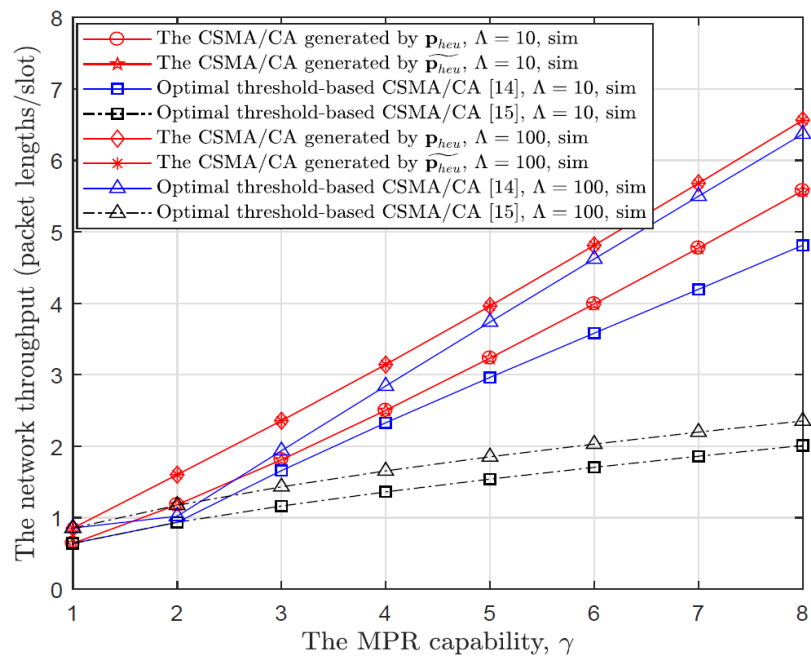
Remark: We set the maximum number of allowed retransmissions to 4.

Convert to CSMA/CA

To convert the generalized p -persistent CSMA to a CSMA/CA scheme for IEEE 802.11-like networks, we require each user to **maintain contention window n with the constant size $W_n = \lfloor 2/p_n - 1 \rfloor$** if $p_n > 0$ for $n = 0, 1, \dots, c - 1$.



The Generalized p -persistent CSMA



The Converted CSMA/CA